

- 1.) C    2.) B    3.) A    4.) E    5.) D

II a)

$$\omega_0^2 = \omega_{p1} \omega_{p2}$$

$$A_s = 18 \text{ dB}$$

$$\Omega_5 = \frac{\omega_{s1} - \omega_{s2}}{\omega_{p1} - \omega_{p2}} = 12.02$$

$$A_p = 3 \text{ dB}$$

$$\omega_{s1} = 2\pi \times 160 \text{ rad/s}$$

$$A(1) = 3 \text{ dB} \Leftrightarrow 10 \log(1 + \epsilon^2) = 3 \text{ dB} \Rightarrow \epsilon = 1$$

$$B = \omega_{p2} - \omega_{p1} = 400 \times 2\pi$$

$$\omega_{p1} = 2\pi \times 800 \text{ rad/s}$$

$$\omega_{s2} = 2\pi \times 5000 \text{ rad/s}$$

$$A(12.02) = 18 \text{ dB} \Leftrightarrow 10 \log(1 + 12.02^{2m}) \Rightarrow m = 1$$

$$\omega_{p2} = 2\pi \times 1200 \text{ rad/s}$$

$$\omega_{p1} \omega_{p2} = \omega_{s1} \omega_{s2} \text{ Não se verifica}$$

$$\omega_{s1} = \frac{\omega_{p1} \omega_{p2}}{\omega_{s2}} = 192 \cdot 2\pi //$$

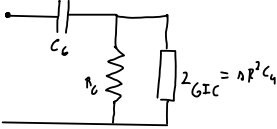
$$T(s) = \frac{1}{H(s)} \Big|_{s = \frac{\lambda^2 + \omega_0^2}{B\lambda}} = \frac{B\lambda}{\lambda^2 + B\lambda + \omega_0^2} = \frac{2513\lambda}{\lambda^2 + 2513\lambda + 37.89 \times 10^6}$$

b) Para  $m=1$  Cutoff e Butter não iguais

$$A_c(\Omega) = 10 \log(1 + \epsilon^2 \Omega^2)$$

$$A_B(\Omega) = 10 \log(1 + \epsilon^2 \Omega^2) //$$

c) 
$$Y_{GTC} = \frac{\frac{1}{R} \cdot \frac{1}{R} \cdot \frac{1}{R}}{\frac{1}{R^2 C_4 \lambda} \cdot \frac{1}{R}} = \frac{1}{R^2 C_4 \lambda}$$



$$\frac{R_6 // \lambda R^2 C_4}{R_6 // \lambda R^2 C_4 + \frac{1}{\lambda C_6}} = \frac{\lambda^2}{\lambda^2 + \frac{1}{R_6 C_6} \lambda + \frac{1}{R^2 C_4 C_6}}$$

$$\omega_0^2 = \frac{1}{R^2 C_4 C_6} \Rightarrow C_4 = 3.957 \text{ nF}$$

$$\frac{\omega_0}{Q} = \frac{1}{R_6 C_6} \Leftrightarrow R_6 = 14.07 \text{ k}\Omega$$

d) Trazer de  $V_2$  (Saida do Amplificador)

III a) FIR - Estável -  $y_m = 2x_m + 0.4x_{m-1} + 0.8y_{m-2} + 0.4x_{m-3} + 2x_{m-4}$

b) 
$$T(e^{j\omega T}) = 2 + 0.4e^{-j\omega T} + 0.8e^{-j2\omega T} + 0.4e^{-j3\omega T} + 2e^{-j4\omega T}$$
  

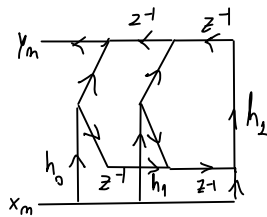
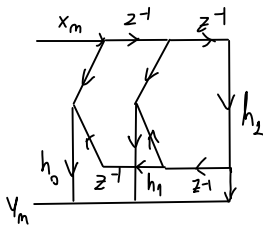
$$= e^{-2j\omega T} (2e^{2j\omega T} + 2e^{2j\omega T} + 0.4e^{j\omega T} + 0.4e^{-j\omega T} + 0.8) =$$
  

$$= e^{-2j\omega T} (0.8 + 4 \cos(2\omega T) + 0.8 \cos(\omega T))$$

$$\varphi = -2\omega T$$

$$Z = -\frac{\partial \varphi}{\partial \omega} = 2T = 40 \mu\text{s} \quad 0.8 + 4 + 0.8 = 5.6 \text{ em DC}$$

c)



d) 
$$\Delta \delta = 2\pi (f_2 - f_1) T = 0.3142 \quad \frac{4\pi}{N} \quad \Delta \delta \approx \frac{4\pi}{N} \Rightarrow N > \frac{4\pi}{\Delta \delta} \quad N = 40 \Rightarrow m > 39$$

IV a) Parte de  $\omega$  em

$$\omega = \frac{1}{RC} = 6.25 \text{ K rad/s}$$

b) Controlo da amplitude das oscilações

Vem com menos distorção!

c) Não afectam  $x_D$

Apenas variam uma componente de uma saída de Ampt