

P1) a) $0 = 0.0087x(4-x)$

PE ① $x=0$

② $x=4$

b)

c) $\dot{x} = \alpha x(4-x)$

$$\ddot{x} = \frac{d}{dt} (4\alpha x - \alpha x^2) =$$

$$= 4\alpha \dot{x} - \alpha \cdot 2 \cdot \dot{x} \cdot x =$$

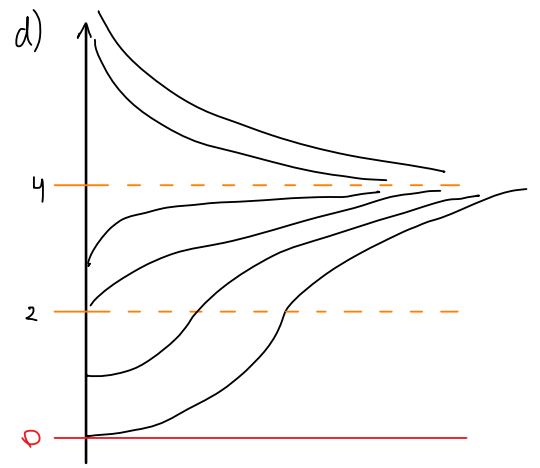
$$= 2\alpha \dot{x} (2-x) = 2\alpha^2 x(4-x)(2-x)$$

$$x=0$$

$$x=2$$

$$x=4$$

		0		2		4	
x	ND	m_1	$\nearrow \cup$	m_1	$\searrow \cap$	m_1	$\searrow \cup$
$\dot{x}$	ND	0	+	0	+	0	-
$\ddot{x}$	ND	0	+	0	-	0	+



d) $x(t+\Delta t) = x(t) + \Delta t \dot{x}(t) \cdot K$

$$\sum_{\Delta t \neq 0} \Delta t \neq 0 \Rightarrow K = \frac{1}{20} \quad \dot{x} = \frac{1}{20} x(t)$$

$$\hookrightarrow 2x(t)$$

P2) a)

$$Y \cdot \Delta \cdot (1+0.5) = U(1-\Delta)$$

$$X(1+0.5) = U$$

$$Y = X(1-\Delta)$$

$$\ddot{x} = u - \dot{x} \cdot 0.5$$

$$x_1 = x$$

$$x_2 = \dot{x} = \dot{x}_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & -0.5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$

$$y = \begin{bmatrix} 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

b) $y = x - \dot{x}$

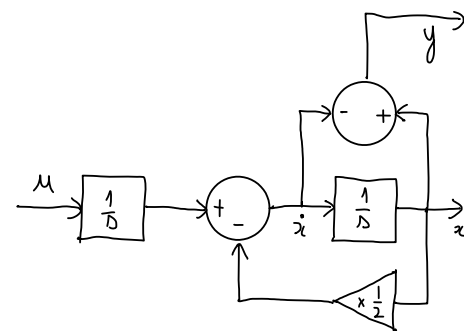
$$\ddot{x} = u - 0.5 \dot{x}$$

$$\downarrow$$

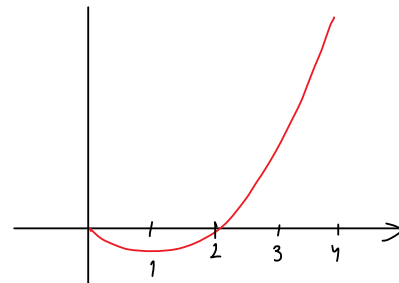
$$\dot{x} = -0.5x + \int u$$

$$\downarrow$$

$$x = \int (-0.5x + \int u)$$



c)



P3)

a) $m_2 \ddot{z}_2 = -\beta \dot{z}_2 - K(z_2 - z_1)$

$$\begin{cases} m_1 \ddot{z}_1 = -\beta \dot{z}_1 - K(z_1 - z_2) + u \\ \downarrow \\ \dot{z}_2 = -\frac{\beta}{m_1} z_2 - \frac{K}{m_1} z_1 + \frac{K}{m_1} z_3 + \frac{1}{m_1} u \\ \downarrow \\ \dot{z}_1 = -\frac{\beta}{m_2} z_1 - \frac{K}{m_2} z_3 + \frac{K}{m_2} z_1 \end{cases}$$

b) $x_1 = z_1$

$$\begin{cases} x_2 = \dot{z}_1 = \dot{x}_1 \\ x_3 = z_2 \\ x_4 = \dot{z}_2 = \dot{x}_3 \end{cases}$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \\ \dot{x}_4 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ \frac{K}{m_1} & -\frac{\beta}{m_1} & \frac{K}{m_1} & 0 \\ 0 & 0 & 0 & 1 \\ \frac{K}{m_2} & 0 & -\frac{K}{m_2} & -\frac{\beta}{m_2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{1}{m_1} \\ 0 \\ 0 \end{bmatrix} u$$

c) $L = T - U$

$$T = \frac{1}{2} m_2 (\dot{z}_2)^2 + \frac{1}{2} m_1 (\dot{z}_1)^2$$

$$U = \frac{1}{2} K (z_2 - z_1)^2$$

$$\frac{\partial L}{\partial z_1} = K(z_2 - z_1)$$

$$\frac{\partial L}{\partial \dot{z}_1} = m_1 \dot{z}_1$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{z}_1} \right) = m_1 \ddot{z}_1$$

1:

$$m_1 \ddot{z}_1 - K(z_2 - z_1) = 0$$

$$\frac{\partial L}{\partial z_2} = -K(z_2 - z_1)$$

$$\frac{\partial L}{\partial \dot{z}_2} = m_2 \dot{z}_2$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{z}_2} \right) = m_2 \ddot{z}_2$$

$$m_2 \ddot{z}_2 + K(z_2 - z_1) = 0$$

P4)

① $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \quad \lambda_1 = 1, \lambda_2 = -1 \Rightarrow \text{Ponto de Sela}$

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \Rightarrow B$$

② $A = \begin{bmatrix} 0 & 1 \\ -2 & -0.6 \end{bmatrix} \quad \lambda = -3 \pm 1.38j$

foco estável

C

③ $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad \lambda_1 = j\sqrt{2}, \lambda_2 = -j\sqrt{2} \Rightarrow \text{Centro}$

$$\dot{x}_2 = 2x_1 \Rightarrow \frac{\partial \dot{x}_2}{\partial x_1} = 2, \frac{\partial \dot{x}_2}{\partial x_2} = 0$$

D

④ $A = \begin{bmatrix} -\frac{5}{3} & -\frac{4}{3} \\ \frac{4}{3} & \frac{5}{3} \end{bmatrix} \quad \lambda_1 = -1, \lambda_2 = 1 \Rightarrow \text{Ponto de sela}$

A

⑤ $A = \begin{bmatrix} 0 & 1 \\ -2 & 0 \end{bmatrix} \quad \lambda = \pm j\sqrt{2} \Rightarrow \text{Centro}$

$$\dot{x}_2 = -2x_1 \Rightarrow \frac{\partial \dot{x}_2}{\partial x_1} = -2 \Rightarrow F$$

⑥ $A = \begin{bmatrix} 0 & -1 \\ 2 & 0.6 \end{bmatrix} \quad E$